

# Numeric certified algorithm for computing the topology of projections of real space curves

Rémi Imbach, Guillaume Moroz and Marc Pouget

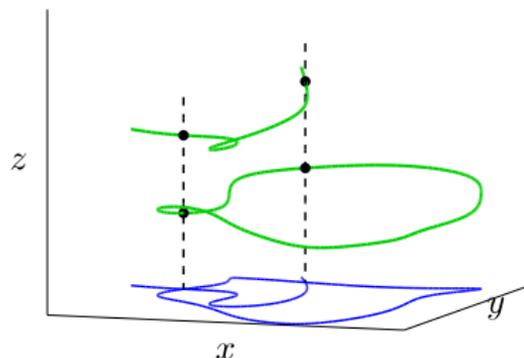
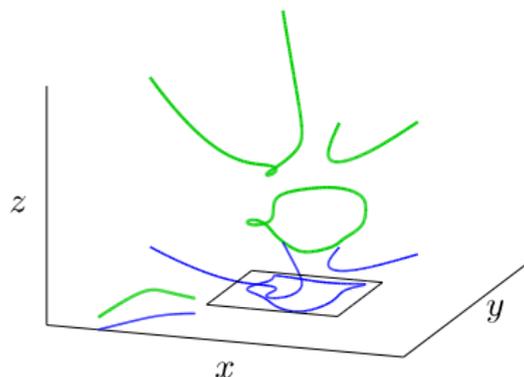


# Projection and Apparent Contour

Curve defined as the intersection of two algebraic surfaces:

$$\mathcal{C} : \begin{cases} p(x, y, z) = 0 \\ q(x, y, z) = 0 \end{cases}, (x, y, z) \in \mathbb{R}^3$$

Projection in the plane:  $\mathcal{B} = \pi_{(x,y)}(\mathcal{C})$

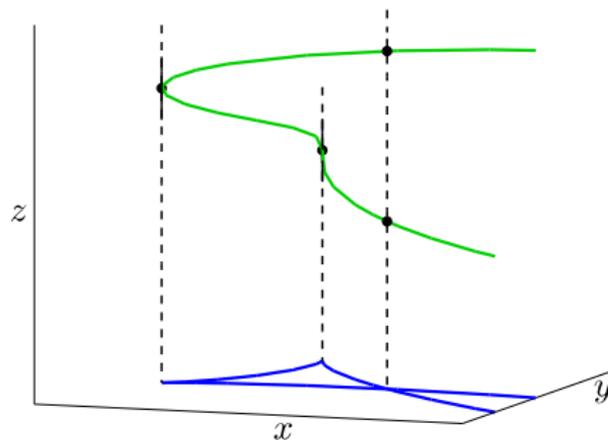
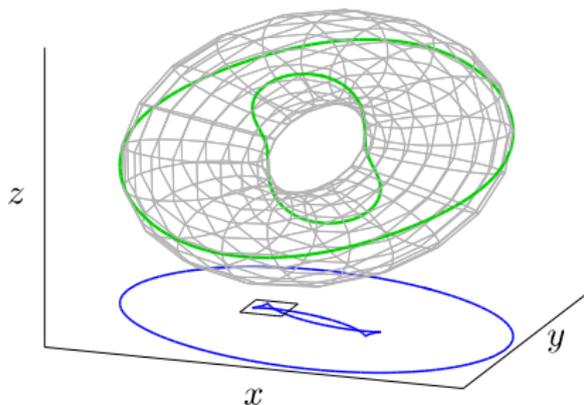


# Projection and Apparent Contour

Curve defined as the intersection of two algebraic surfaces:

$$C : \begin{cases} p(x, y, z) = 0 \\ p_z(x, y, z) = 0 \end{cases}, (x, y, z) \in \mathbb{R}^3, \quad p_z = \frac{\partial p}{\partial z}$$

Apparent contour:  $\mathcal{B} = \pi_{(x,y)}(C)$

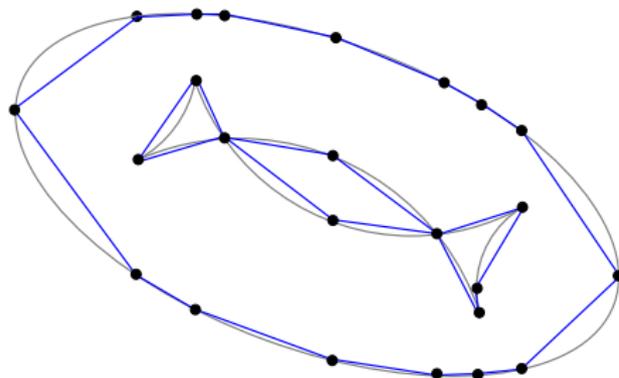
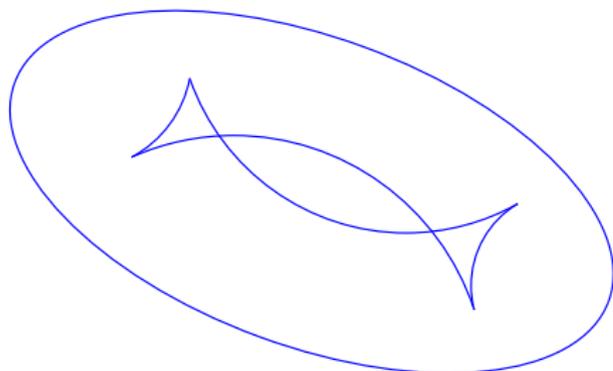


## Computing topology of a real plane curve $\mathcal{B}$

$$\mathcal{B} = \{(x, y) \in \mathbb{R}^2 \mid f(x, y) = 0\}$$

$$\text{Singularities: } \{(x, y) \in \mathbb{R}^2 \mid f(x, y) = f_x(x, y) = f_y(x, y) = 0\}$$

- Path tracking methods fail near singularities

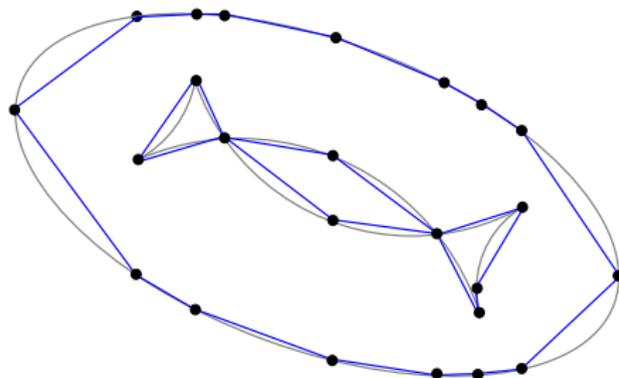
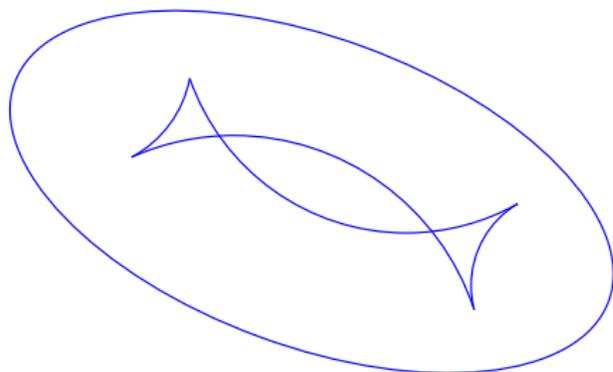


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- Path tracking methods fail near singularities
- Symbolic methods
  - CAD requires : computing with algebraic numbers

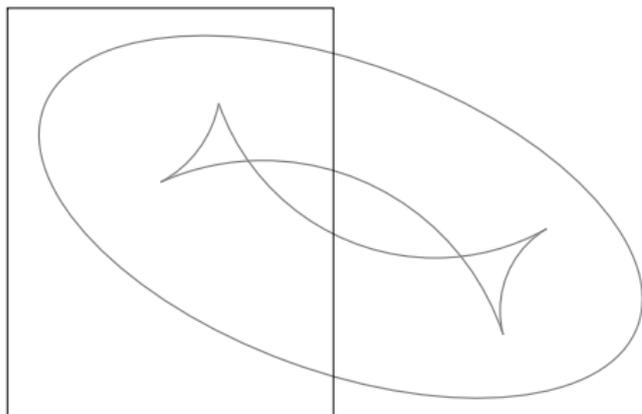


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### A general framework

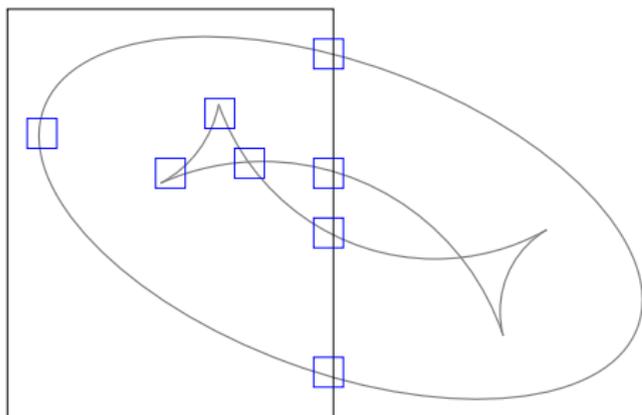
- ① Restrict to a compact  $\mathbf{B}_0$
- ① Isolate in boxes:
  - boundary points
  - $x$ -critical points
  - singularities
- ② Compute topology around singularities
- ③ Connect boxes

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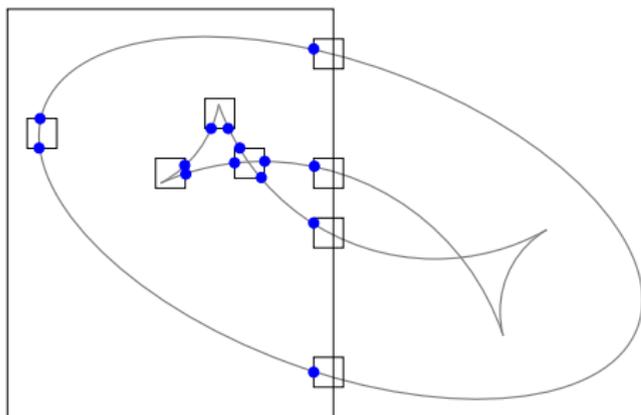
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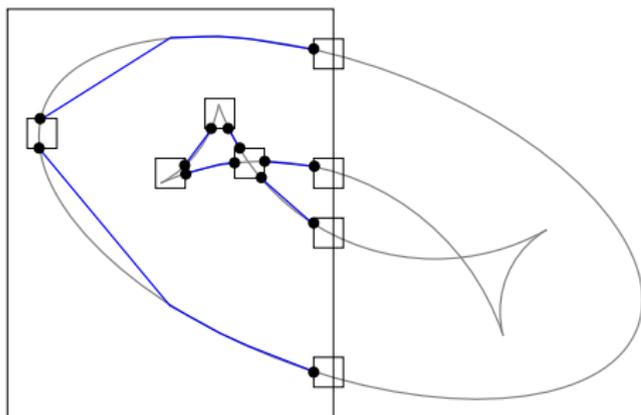
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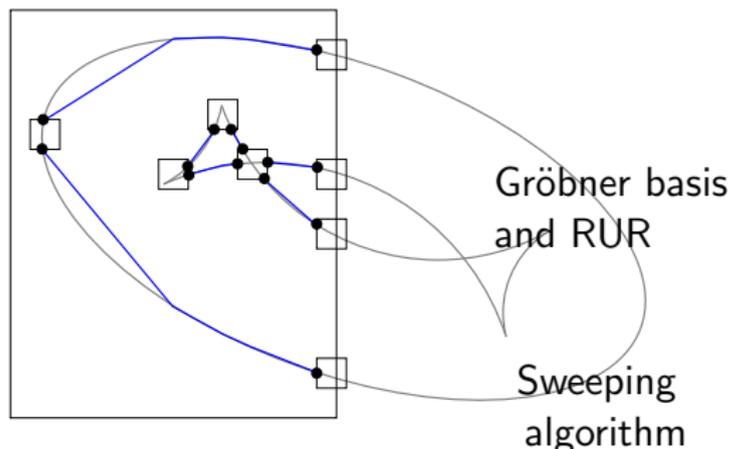
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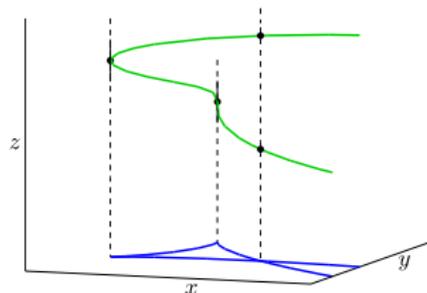
## ISOTOP



## A general framework

- ① Restrict to a compact  $\mathbf{B}_0$
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- ② Compute topology around singularities
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## When $\mathcal{B}$ is a projection or an apparent contour



Geometric characterization of nodes and cusps:

- 4D square system
- 0-dim solver

Certified numerical tools:

- 0-dim solver: subdivision

### ① Isolate in boxes:

- boundary points
- $x$ -critical points
- [singularities](#)

## When $\mathcal{B}$ is a projection or an apparent contour

Enclosing  $\mathcal{C}$  in a sequence of boxes:

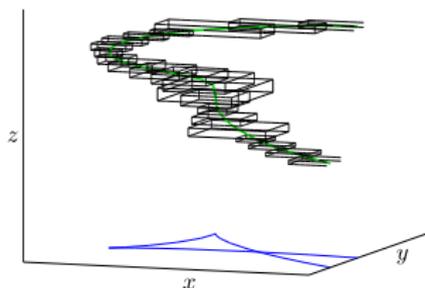
- 1-dim solver
- 1 point on each C.C.: 0-dim solver

Geometric characterization of nodes and cusps:

- 4D square system
- 0-dim solver
- **Restriction of the solving domain**

Certified numerical tools:

- 0-dim solver: subdivision
- 1-dim solver: path tracker



### ① Isolate in boxes:

- boundary points
- $x$ -critical points
- **singularities**

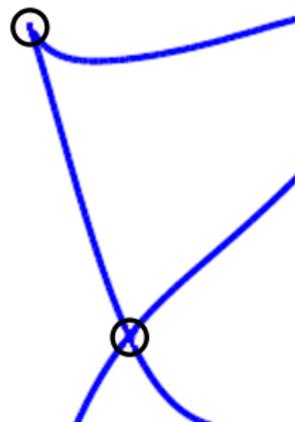
## Isolating singularities

$$\mathcal{B} = \{(x, y) \in \mathbb{R}^2 \mid r(x, y) = 0\},$$

Singularities of  $\mathcal{B}$  are the solutions of:

$$\begin{cases} r(x, y) = 0 \\ \frac{\partial r}{\partial x}(x, y) = 0 \\ \frac{\partial r}{\partial y}(x, y) = 0 \end{cases}$$

... that is over-determined.



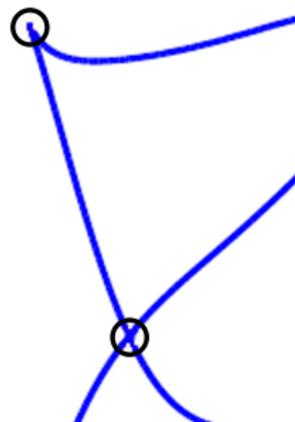
## Isolating singularities

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Singularities of  $\mathcal{B}$  are the solutions of:

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... that has solutions of multiplicity 2.



## Isolating singularities of an apparent contour

$\mathcal{B} = \{(x, y) \in \mathbb{R}^2 \mid r(x, y) = 0\}$ , where  $r(x, y) = \text{Res}(p, p_z, z)(x, y)$

Singularities of  $\mathcal{B}$  are the solutions of:

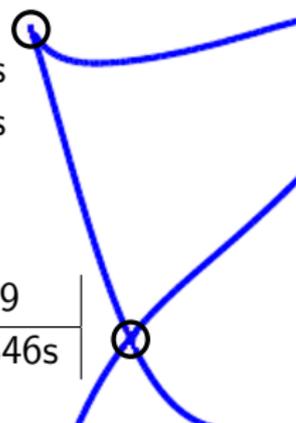
$$\begin{cases} r(x, y) = 0 \\ \frac{\partial r}{\partial x}(x, y) = 0 \end{cases} \quad \text{s.t.} \quad \frac{\partial r}{\partial y}(x, y) = 0$$

... that has solutions of multiplicity 2.

$p$ ,	degree 6,	bit-size 8,	84 monomials
$r$ ,	degree 30,	bit-size 111,	496 monomials
$\frac{\partial r}{\partial x}, \frac{\partial r}{\partial y}$ ,	degree 29,	bit-size 115,	465 monomials

degree of $p$	5	6	7	8	9
time with RSCube*	3.1s	32s	254s	1898s	9346s

\* F.Rouillier



## Isolating singularities of an apparent contour

$\mathcal{B} = \{(x, y) \in \mathbb{R}^2 \mid r(x, y) = 0\}$ , where  $r(x, y) = \text{Res}(p, p_z, z)(x, y)$

Singularities of  $\mathcal{B}$  are the **regular** solutions of:

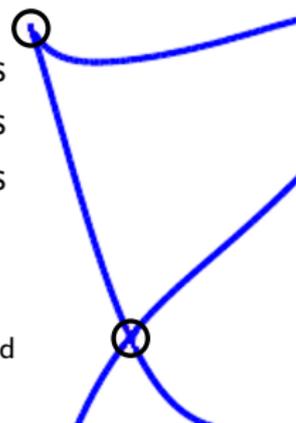
$$(\mathcal{S}_2) \begin{cases} s_{10}(x, y) = 0 \\ s_{11}(x, y) = 0 \end{cases} \quad \text{s.t. } s_{22}(x, y) \neq 0$$

... where  $s_{10}, s_{11}, s_{22}$  are coefficients in the subresultant chain.

$p$ ,	degree 6,	bit-size 8,	84 monomials
$r$ ,	degree 30,	bit-size 111,	496 monomials
$\frac{\partial r}{\partial x}, \frac{\partial r}{\partial y}$ ,	degree 29,	bit-size 115,	465 monomials
$s_{11}, s_{10}$ ,	degree 20,	bit-size 89,	231 monomials
$s_{22}$ ,	degree 12,	bit-size 65,	91 monomials

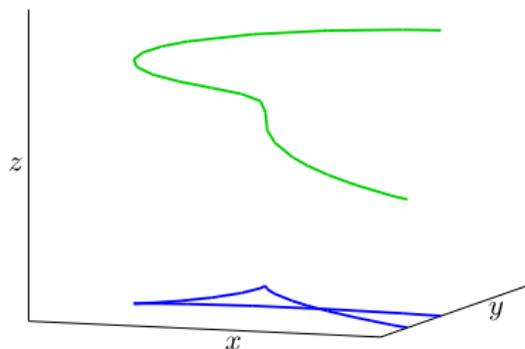
- [IMP15] Rémi Imbach, Guillaume Moroz, and Marc Pouget.  
 Numeric certified algorithm for the topology of resultant and discriminant curves.

Research Report RR-8653, Inria, April 2015.



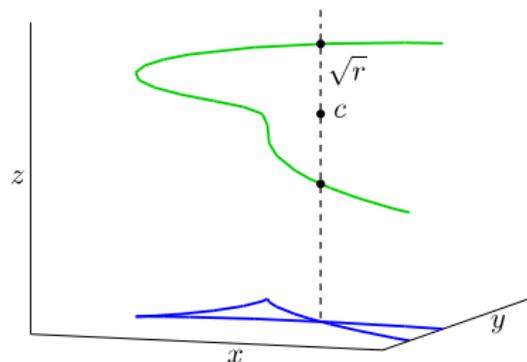
## Isolating singularities . . . : the ball system

$$\mathcal{B} = \{(x, y) \in \mathbb{R}^2 \mid \exists z \in \mathbb{R} \text{ s.t. } (x, y, z) \in \mathcal{C}\}$$



## Isolating singularities . . . : the ball system

$$\mathcal{B} = \{(x, y) \in \mathbb{R}^2 \mid \exists z \in \mathbb{R} \text{ s.t. } (x, y, z) \in \mathcal{C}\}$$



$c$ : center of  $z_1, z_2$   
 $r = \|cz_1\|_2^2$

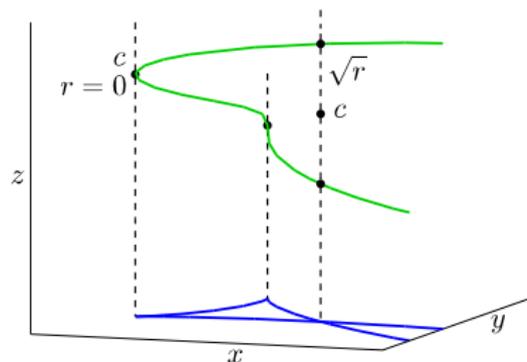
Let  $(x, y)$  be:

- a node:  $(x, y, z_1), (x, y, z_2) \in \mathcal{C}$ , with  $z_1 \neq z_2$

$$z_1 = c - \sqrt{r}, z_2 = c + \sqrt{r}$$

## Isolating singularities ...: the ball system

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 $z_1 = c - \sqrt{r}, z_2 = c + \sqrt{r}$
- a cusp:  $(x, y, z_1), (x, y, z_2) \in \mathcal{C}$ , with  $z_1 = z_2$   
 $z_1 = c - \sqrt{r}, z_2 = c + \sqrt{r}$

## Isolating singularities . . . : the ball system

$$\mathcal{B} = \{(x, y) \in \mathbb{R}^2 \mid \exists z \in \mathbb{R} \text{ s.t. } (x, y, z) \in \mathcal{C}\}$$

Singularities of  $\mathcal{B}$  are the **regular** solutions of:

$$(\mathcal{S}_4) \begin{cases} \frac{1}{2}(p(x, y, c + \sqrt{r}) + p(x, y, c - \sqrt{r})) = 0 \\ \frac{1}{2\sqrt{r}}(p(x, y, c + \sqrt{r}) - p(x, y, c - \sqrt{r})) = 0 \\ \frac{1}{2}(p_z(x, y, c + \sqrt{r}) + p_z(x, y, c - \sqrt{r})) = 0 \\ \frac{1}{2\sqrt{r}}(p_z(x, y, c + \sqrt{r}) - p_z(x, y, c - \sqrt{r})) = 0 \end{cases}$$

Let  $(x, y)$  be:

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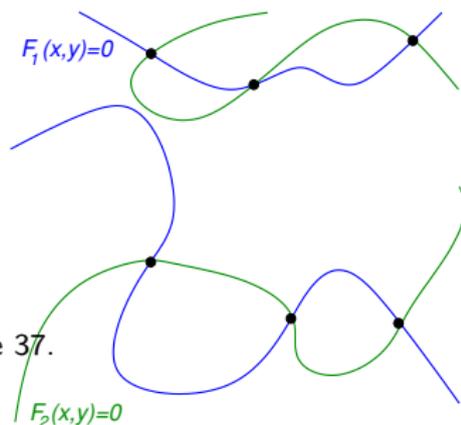
- equations of  $(\mathcal{S}_4)$  are polynomials
- 4 equations in 4 unknowns

## Certified numerical tools: 0-dim solver

$F : \mathbb{R}^n \rightarrow \mathbb{R}^n$ ,  $F$  polynomial,

- find zeros of  $F$ : find  $\{X \in \mathbb{R}^n \mid F(X) = 0\}$

[Neu90] [Arnold Neumaier](#).  
*Interval methods for systems of equations*, volume 37.  
Cambridge university press, 1990.

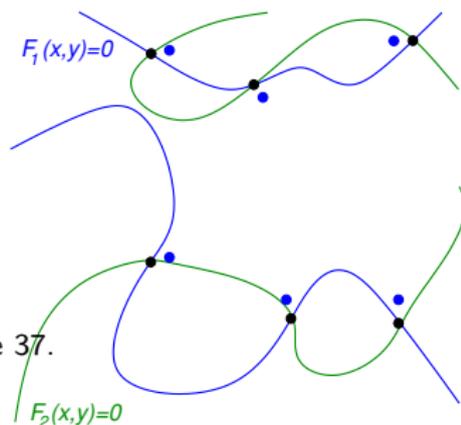


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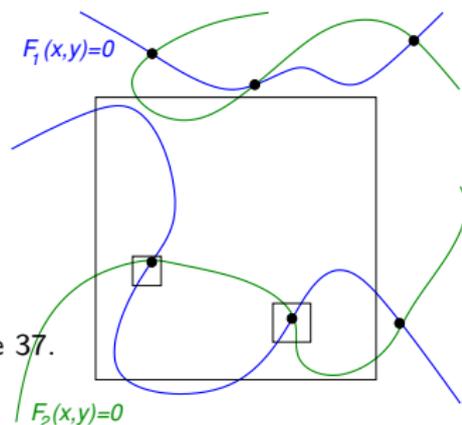


## Certified numerical tools: 0-dim solver

$F : \mathbb{R}^n \rightarrow \mathbb{R}^n$ ,  $F$  polynomial,  $\mathbf{X}_0$  a compact of  $\mathbb{R}^n$

- find zeros of  $F$ : find  $\{X \in \mathbb{R}^n | F(X) = 0\}$
- Isolate zeros of  $F$  in boxes  $\{\mathbf{X}_1, \dots, \mathbf{X}_n\}$  such that
  - each  $\mathbf{X}_k$  contains a unique zero of  $F$
  - each zero of  $F$  in  $\mathbf{X}_0$  is in a unique box  $\mathbf{X}_k$

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Interval Arithmetic:  $\mathbf{x} \subset \mathbb{R}$ ,  $\mathbf{X} \subset \mathbb{R}^n$

- multi-dimensional extension of interval : box  $\mathbf{X} \subset \mathbb{R}^n$

$$\mathbf{X} = \mathbf{x}_1 \times \dots \times \mathbf{x}_n = [l(x_1), r(x_1)] \times \dots \times [l(x_n), r(x_n)]$$

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## Certified numerical tools: 0-dim solver

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Interval Arithmetic:  $\mathbf{x} \subset \mathbb{R}$ ,  $\mathbf{X} \subset \mathbb{R}^n$

- multi-dimensional extension of interval : box  $\mathbf{X} \subset \mathbb{R}^n$
- interval arithmetic operators

$$\mathbf{x} = [l(x), r(x)], \mathbf{y} = [l(y), r(y)], \mathbf{x} + \mathbf{y} = [l(x) + l(y), r(x) + r(y)]$$

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## Certified numerical tools: 0-dim solver

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**Interval Arithmetic:**  $\mathbf{x} \subset \mathbb{R}$ ,  $\mathbf{X} \subset \mathbb{R}^n$ ,  $F(\mathbf{X}) \supseteq \{F(X) | X \in \mathbf{X}\}$

- multi-dimensional extension of interval : box  $\mathbf{X} \subset \mathbb{R}^n$
- interval arithmetic operators
- interval evaluation of  $F : \mathbb{R}^n \rightarrow \mathbb{R}^n$  :  $F(\mathbf{X}) \supseteq \{F(X) | X \in \mathbf{X}\}$

[Neu90] [Arnold Neumaier](#).

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## Certified numerical tools: 0-dim solver

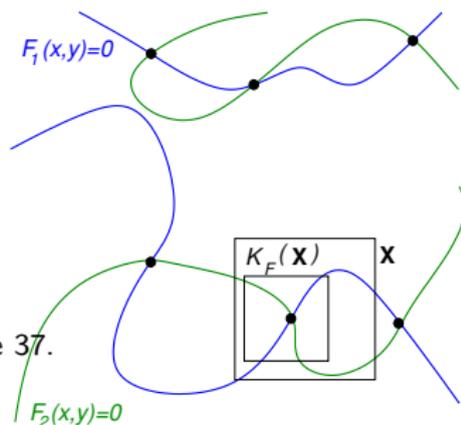
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Interval Arithmetic:  $\mathbf{x} \subset \mathbb{R}$ ,  $\mathbf{X} \subset \mathbb{R}^n$ ,  $F(\mathbf{X}) \supseteq \{F(X) | X \in \mathbf{X}\}$

Krawczik criterion:  $K_F : \mathbf{X} \subset \mathbb{R}^n \mapsto K_F(\mathbf{X}) \subset \mathbb{R}^n$

$K_F(\mathbf{X}) \subset \text{Int}(\mathbf{X}) \Rightarrow K_F(\mathbf{X})$  contains a unique zero of  $F$   
consequence of the Brouwer fixed point theorem.

[Neu90] [Arnold Neumaier](#).  
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## Certified numerical tools: 0-dim solver

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Krawczik criterion:  $K_F : \mathbf{X} \subset \mathbb{R}^n \mapsto K_F(\mathbf{X}) \subset \mathbb{R}^n$

### Subdivision method:

**Input:**  $F : \mathbb{R}^n \rightarrow \mathbb{R}^n$ ,  $\mathbf{X}_0$  box of  $\mathbb{R}^n$

**Output:** A list  $R$  of boxes containing solutions in  $\mathbf{X}_0$  of  $F = 0$

$L := \{\mathbf{X}_0\}$

**Repeat:**

$\mathbf{X} := L.pop$

**If**  $0 \in F(\mathbf{X})$  **then**

**If**  $K_F(\mathbf{X}) \subset \text{Int}(\mathbf{X})$  **then**

            insert  $\mathbf{X}$  in  $R$

**Else If**  $K_F(\mathbf{X}) \cap \mathbf{X} \neq \emptyset$  **then**

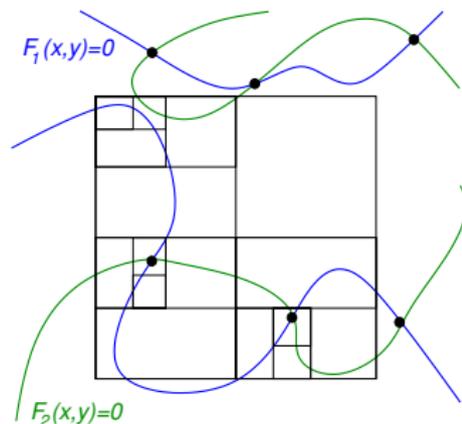
            bisect  $\mathbf{X}$  and insert its sub-boxes in  $L$

**End if**

**End if**

**Until**  $L = \emptyset$

**Return**  $R$



## Certified numerical tools: 0-dim solver

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Interval Arithmetic:  $\mathbf{x} \subset \mathbb{R}$ ,  $\mathbf{X} \subset \mathbb{R}^n$ ,  $F(\mathbf{X}) \supseteq \{F(X) | X \in \mathbf{X}\}$

Krawczik criterion:  $K_F : \mathbf{X} \subset \mathbb{R}^n \mapsto K_F(\mathbf{X}) \subset \mathbb{R}^n$

Subdivision method:

- terminates with a correct result when
  - $F = 0$  has only regular solutions,
  - working at arbitrary precision.
- can be extended to unbounded initial box  $\mathbf{X}_0$
- its cost grows exponentially with  $n$

[Neu90] [Arnold Neumaier](#).

*Interval methods for systems of equations*, volume 37.

Cambridge university press, 1990.

## Certified numerical isolation of singularities

**Datas:** Random dense polynomials of degree  $d$ , bit-size 8

**Subdivision solver:** home made in C++, with boost interval library

- evaluation of polynomials with horner scheme → quick
- evaluation of polynomials at order 2 → sharp

**Numerical results:** Subdivision solving within  $[-1, 1] \times [-1, 1]$

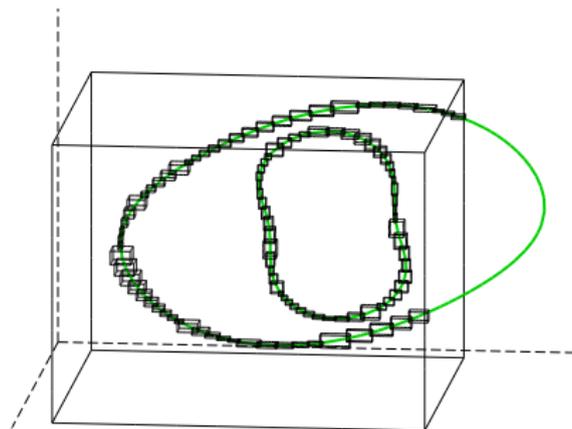
$d$	Sub-resultant system $S_2$	Ball system $S_4$
	t	t
5	0.05	24.8
6	0.50	8.40
7	4.44	43.8
8	37.9	70.2
9	23.1	45.6

means on 5 examples of sequential times in seconds on a Intel(R) Xeon(R) CPU L5640 @ 2.27GHz machine.

## Restriction of the solving domain

Enclose  $\mathcal{C}$ : find a sequence  $\{\mathbf{C}_k\}_{1 \leq k \leq l}$  such that

- $\mathcal{C} \subset \bigcup_k \mathbf{C}_k$ ,
- in each  $\mathbf{C}_k$ ,  $\mathcal{C} \cap \mathbf{C}_k$  is diffeomorphic to a close segment,
- each  $\mathbf{C}_k$  has width less than  $\eta$ .

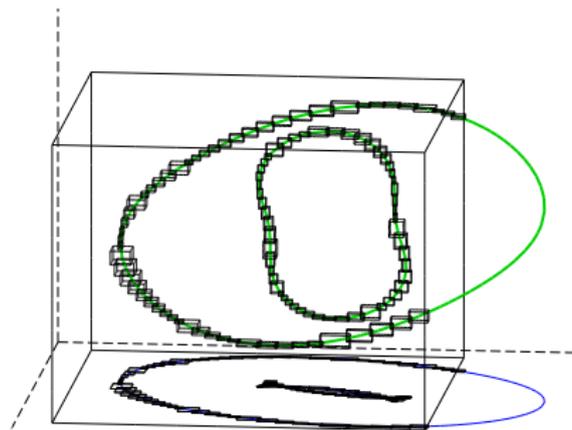


## Restriction of the solving domain

Enclose  $\mathcal{C}$ : find a sequence  $\{\mathbf{C}_k\}_{1 \leq k \leq l}$

→ Enclose  $\mathcal{B}$ : each  $B \in \mathcal{B}$  is in a  $\mathbf{B}_k = \pi_{(x,y)}(\mathbf{C}_k)$

$$\mathbf{C}_k = (\mathbf{x}_k, \mathbf{y}_k, \mathbf{z}_k)$$



## Restriction of the solving domain

Enclose  $\mathcal{C}$ : find a sequence  $\{\mathbf{C}_k\}_{1 \leq k \leq l}$

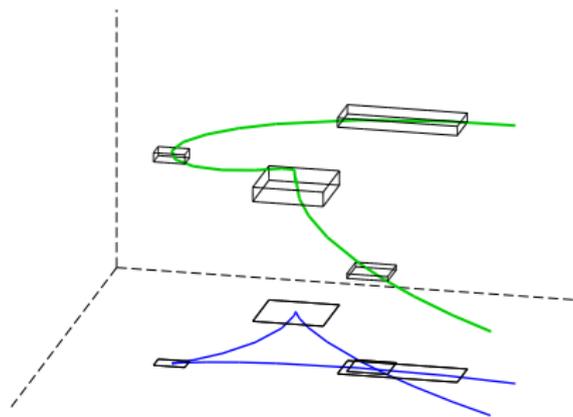
→ Enclose  $\mathcal{B}$ : each  $B \in \mathcal{B}$  is in a  $\mathbf{B}_k = \pi_{(x,y)}(\mathbf{C}_k)$

→ Enclose singularities:

- each cusp is in a  $\mathbf{B}_k$
- each node is in a  $\mathbf{B}_{ij} = \mathbf{B}_i \cap \mathbf{B}_j$

$$\mathbf{C}_k = (\mathbf{x}_k, \mathbf{y}_k, \mathbf{z}_k)$$

$$\mathbf{B}_k = (\mathbf{x}_k, \mathbf{y}_k)$$



## Restriction of the solving domain

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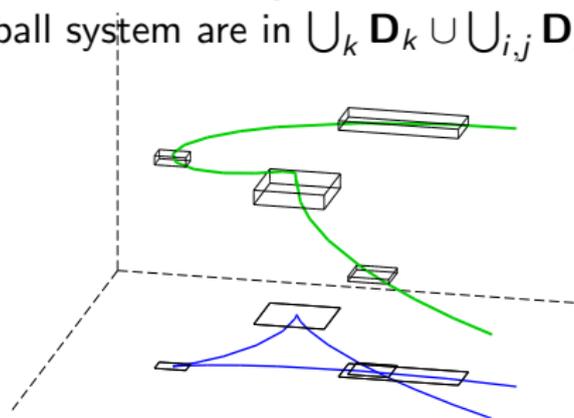
$$\mathbf{B}_k = (\mathbf{x}_k, \mathbf{y}_k)$$

→ Enclose singularities:

- each cusp is in a  $\mathbf{B}_k$   $\mathbf{D}_k = (\mathbf{x}_k, \mathbf{y}_k, \mathbf{z}_k, [0, (\frac{w(\mathbf{z}_k)}{2})^2])$
- each node is in a  $\mathbf{B}_{ij} = \mathbf{B}_i \cap \mathbf{B}_j$   $\mathbf{D}_{ij} = (\mathbf{x}_{ij}, \mathbf{y}_{ij}, \frac{(\mathbf{z}_i + \mathbf{z}_j)}{2}, [0, (\frac{(\mathbf{z}_i - \mathbf{z}_j)}{2})^2])$

→ Enclose solutions of the ball system:

Solutions of the ball system are in  $\bigcup_k \mathbf{D}_k \cup \bigcup_{i,j} \mathbf{D}_{ij}$

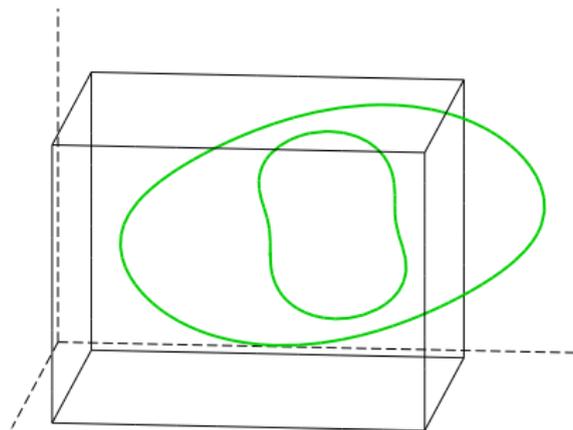


## Certified numerical tools: path tracker

$F : \mathbb{R}^n \rightarrow \mathbb{R}^{n-1}$ ,  $\mathbf{X}_0$  a box of  $\mathbb{R}^n$

$\mathcal{X} = \{X \in \mathbf{X}_0 \mid F(X) = 0\}$  is a smooth curve of  $\mathbb{R}^n$

$\mathcal{X}^1, \dots, \mathcal{X}^m$ : connected components of  $\mathcal{X}$



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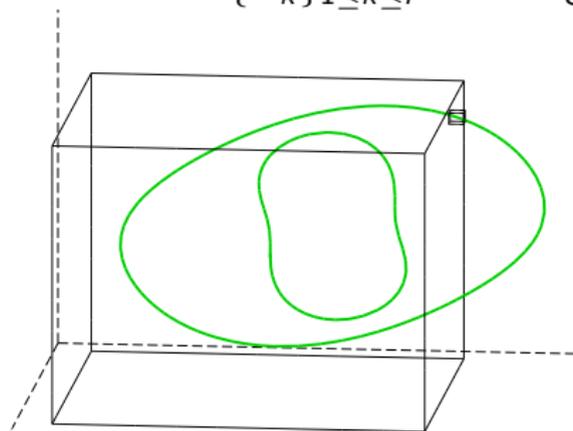
$\mathcal{X}^1, \dots, \mathcal{X}^m$ : connected components of  $\mathcal{X}$

Certified path-tracker:

**Input:**  $F : \mathbb{R}^n \rightarrow \mathbb{R}^{n-1}$ ,  $\mathbf{X}_0$  box of  $\mathbb{R}^n$ ,  $\eta \in \mathbb{R}_*^+$

An initial box  $\mathbf{X} \in \mathcal{X}^i$

**Output:** a sequence of boxes  $\{\mathbf{X}_k\}_{1 \leq k \leq l}$  enclosing  $\mathcal{X}^i$ .



## Certified numerical tools: path tracker

$F : \mathbb{R}^n \rightarrow \mathbb{R}^{n-1}$ ,  $\mathbf{X}_0$  a box of  $\mathbb{R}^n$

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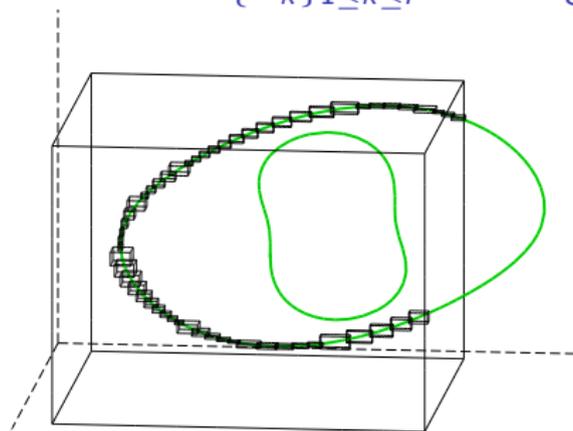
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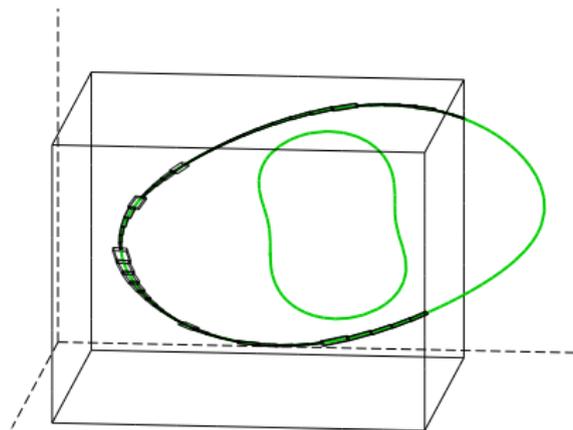
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# Certified numerical tools: path tracker

- [MGGJ13] Benjamin Martin, Alexandre Goldsztejn, Laurent Granvilliers, and Christophe Jermann.  
Certified parallelotope continuation for one-manifolds.  
*SIAM Journal on Numerical Analysis*, 51(6):3373–3401, 2013.



## Enclosing $\mathcal{C}$

$F : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ ,  $\mathbf{B}_0$  a box of  $\mathbb{R}^3$

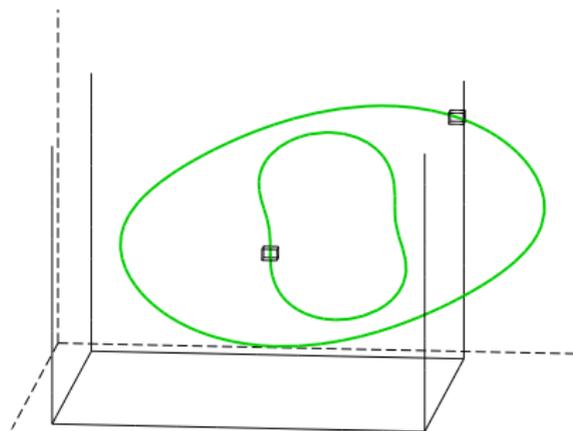
$\mathcal{C} = \{C \in \mathbf{B}_0 \times \mathbb{R} \mid F(X) = 0\}$  is a smooth curve of  $\mathbb{R}^3$

$\mathcal{C}^1, \dots, \mathcal{C}^m$ : connected components of  $\mathcal{C}$

**Assumption (A3):**  $\mathcal{C}$  is compact over  $\mathbf{B}_0$

(A3) holds for generic polynomials  $p, q$

Finding one point on each connected component

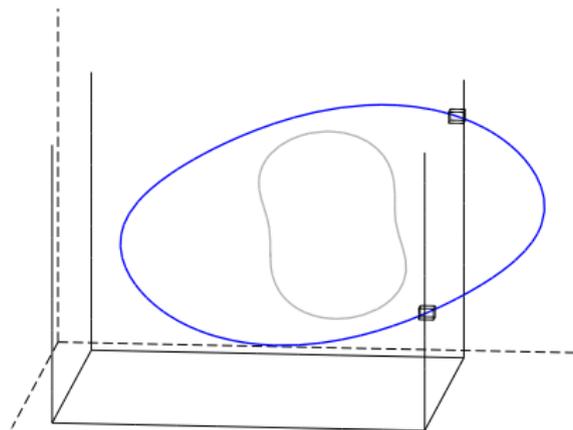


## Finding one point on each connected component

**Assumption (A3):**  $\mathcal{C}$  is compact over  $\mathbf{B}_0$

**Lemma:** If (A3) holds,  $\mathcal{C}^k$  is

- either diffeomorphic to  $[0, 1]$   
 $\Rightarrow$  has 2 intersections with  $\partial\mathbf{B}_0 \times \mathbb{R}$
- or diffeomorphic to a circle  
 $\Rightarrow$  has at least two  $x$ -critical points



## Finding one point on each connected component

**Assumption (A3):**  $\mathcal{C}$  is compact over  $\mathbf{B}_0$

$\mathcal{C} \cap (\partial\mathbf{B}_0 \times \mathbb{R})$  are the solutions of the 4 systems:

**Lemma:** If (A3) holds,  $\mathcal{C}^k$  is

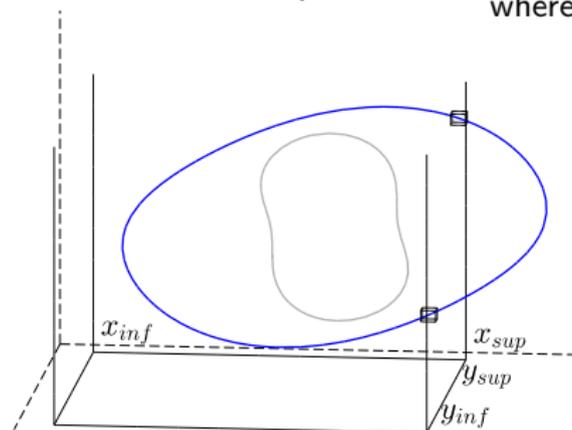
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 $\Rightarrow$  has at least two  $x$ -critical points

$$\begin{cases} p(x = a, y, z) = 0 \\ q(x = a, y, z) = 0 \end{cases}$$

$$\begin{cases} p(x, y = b, z) = 0 \\ q(x, y = b, z) = 0 \end{cases}$$

where  $a \in \{x_{inf}, x_{sup}\}$ ,

$b \in \{y_{inf}, y_{sup}\}$

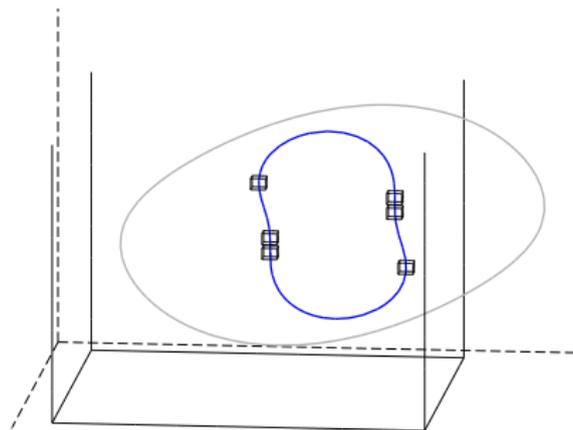


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## Finding one point on each connected component

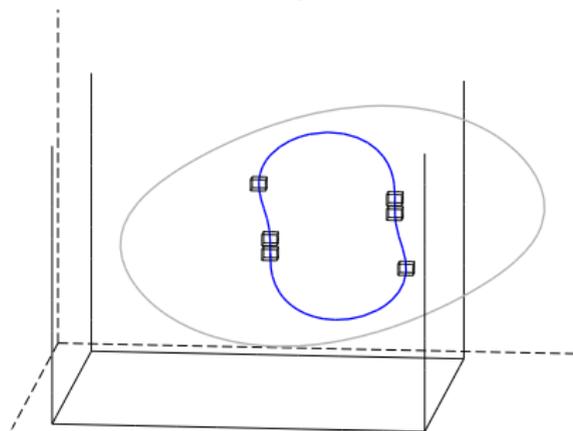
**Assumption (A3):**  $\mathcal{C}$  is compact over  $\mathbf{B}_0$

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- or diffeomorphic to a circle  
 $\Rightarrow$  has at least two  $x$ -critical points

$x$ -critical points of  $\mathcal{C}$  are the solutions of the system:

$$\left\{ \begin{array}{l} p(x, y, z) = 0 \\ q(x, y, z) = 0 \\ \left| \begin{array}{cc} p_y & p_z \\ q_y & q_z \end{array} \right| (x, y, z) = 0 \end{array} \right.$$



# Certified numerical isolation of singularities

Path tracker: prototype in python/cython

Numerical results: solving within  $[-1, 1] \times [-1, 1]$

$d$	Sub-resultant system $\mathcal{S}_2$	Ball system $\mathcal{S}_4$	$\mathcal{S}_4$ with curve tracking
	t	t	t
5	0.05	24.8	1.25
6	0.50	8.40	2.36
7	4.44	43.8	4.13
8	37.9	70.2	5.91
9	23.1	45.6	5.30

means on 5 examples of sequential times in seconds on a Intel(R) Xeon(R) CPU L5640 @ 2.27GHz machine.

## Perspectives

- Using the enclosure of  $\mathcal{C}$  to recover the topology of  $\mathcal{B}$
- Projections of curves of  $\mathbb{R}^n$ , with  $n > 3$

Questions?